

V1.01

		1
		2
1		4

6.4		35
6.5		36
6.6		37
7		38
7.1		38
8		39
8.1		39
8.2		39
8.3		40
8.4		42
		43

/

“ / ” 4

“ ” 4

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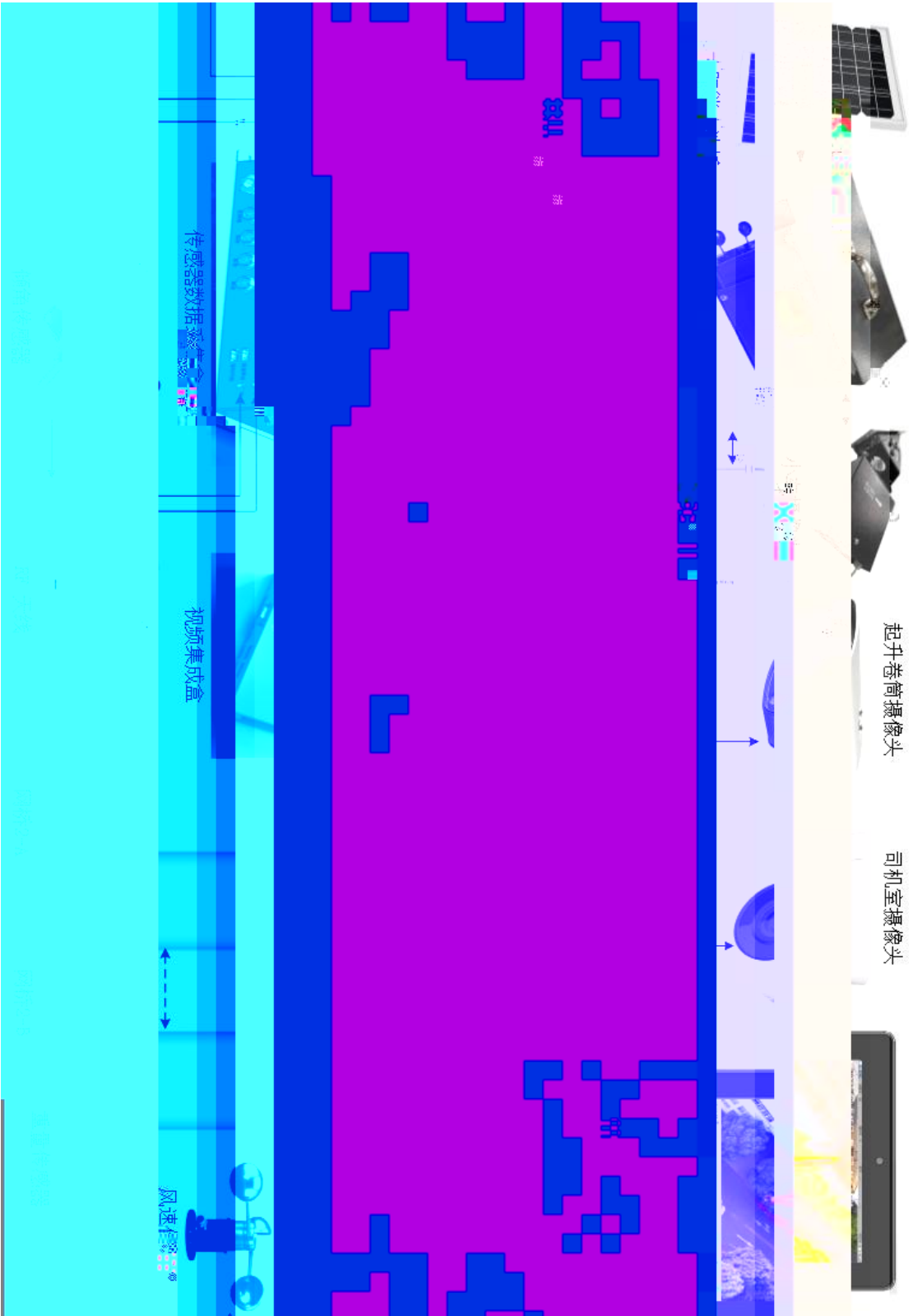
3

1

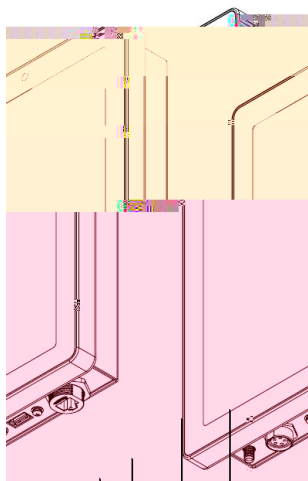
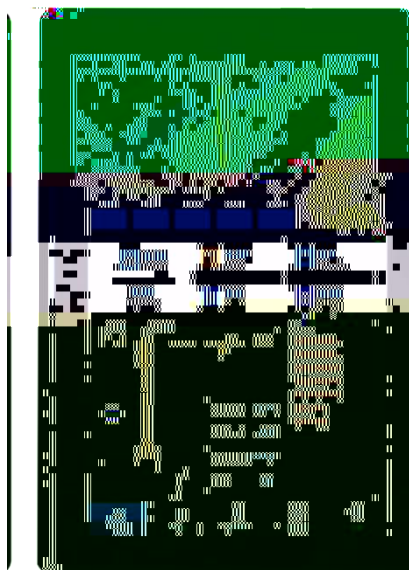
TCSMS100

“ ”

- 4
- ≥ 72
-
- ≥ 30
- U
-
-
-

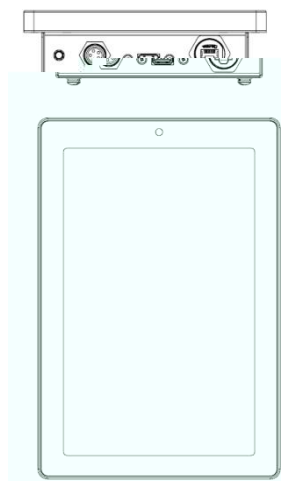


1.1



USB
4G

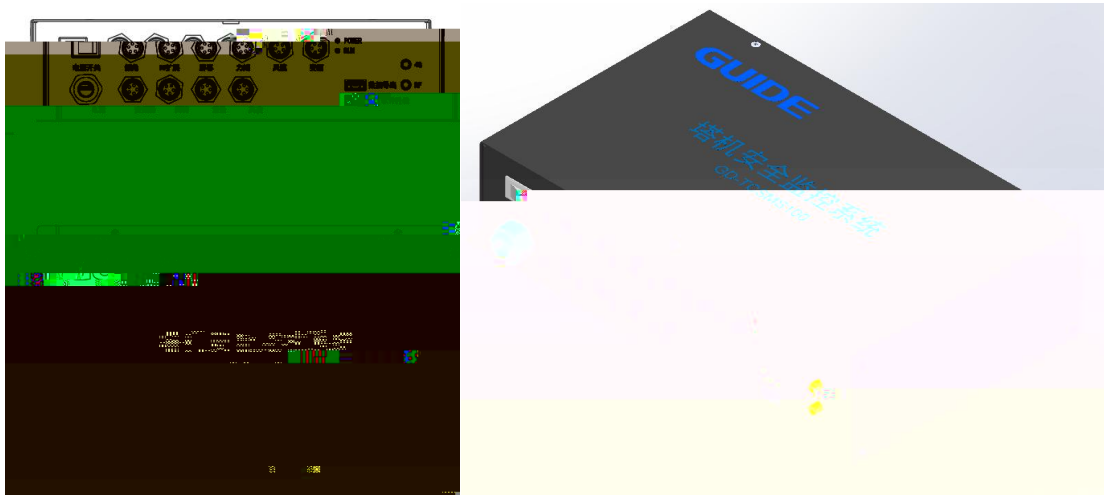
10.1



RK3288



1.2

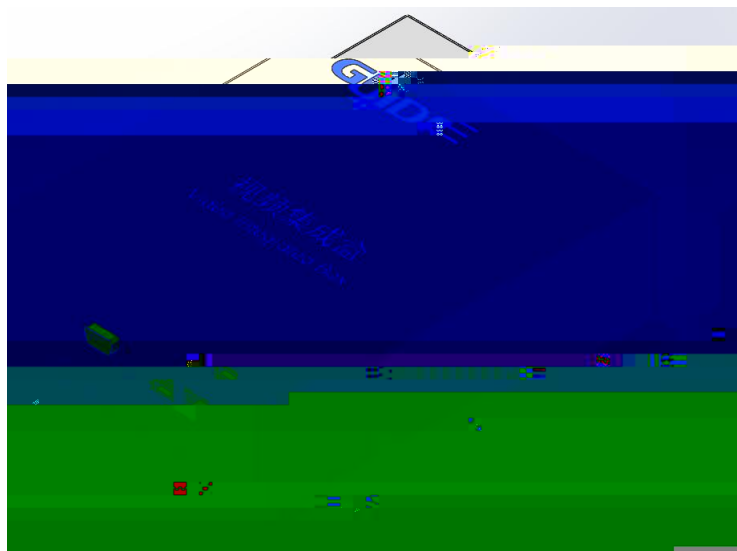


		1	2	3	4	5
	5	+5V	GND			
	5	+5V	GND			
	5	+5V	GND	485+ /	485 -	+15V
	5	+5V	GND			+15V
	5	+5V	GND			+15V
	5	+5V	GND			+15V
	5	+5V	GND	485+	485 -	+15V
	5	+5V	GND	485+	485 -	+15V
	5		GND	232_TX	232_RX	+15V
10	5	+5V	GND	CANH	CANL	+15V

ARM

4G DTU

1.3

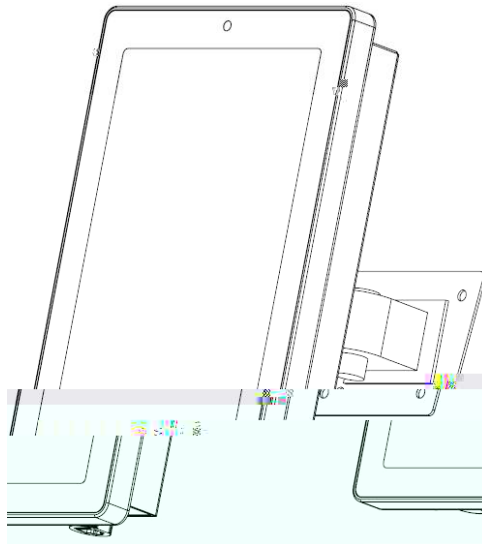


1.4



2

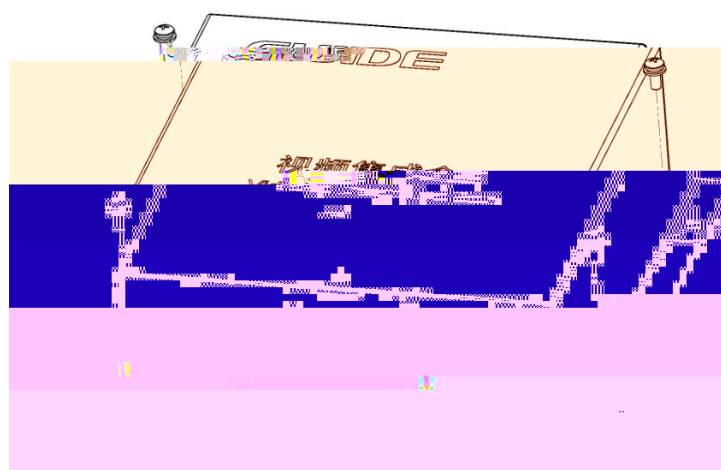
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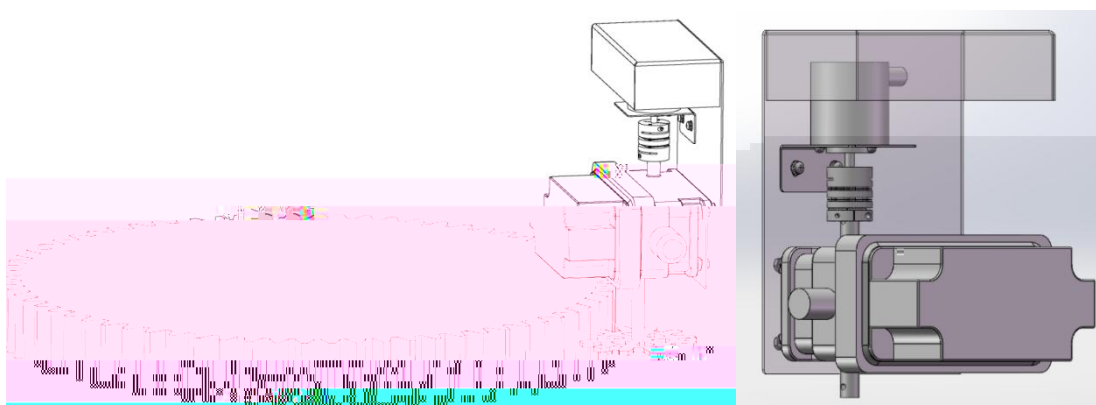
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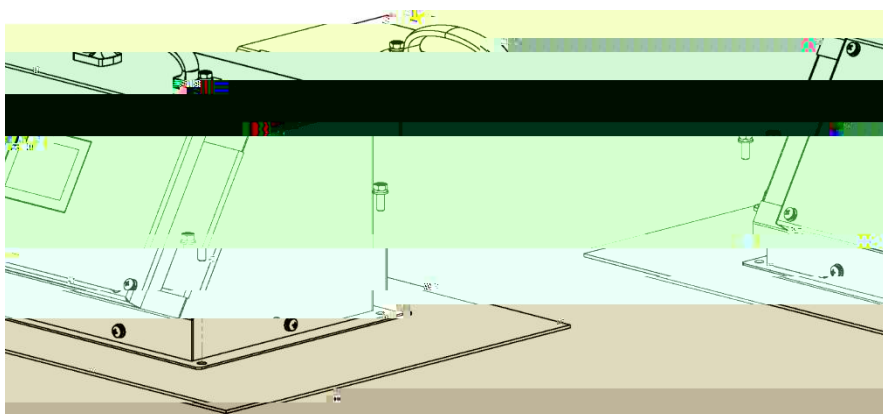
2.3



2.4



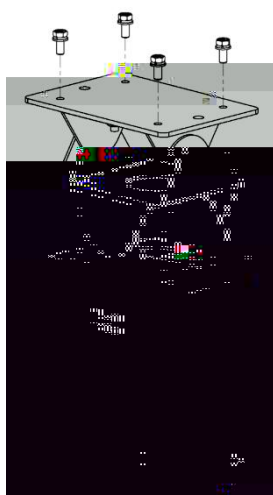
2.5



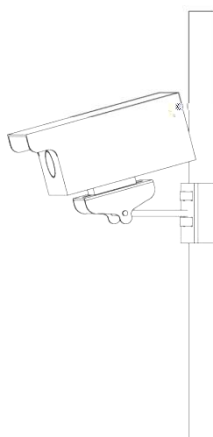
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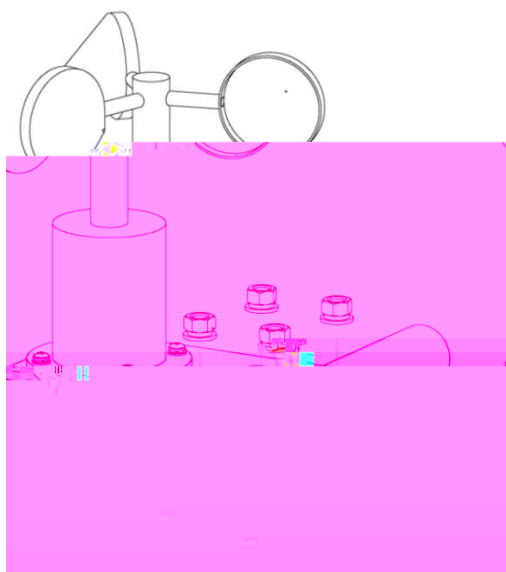
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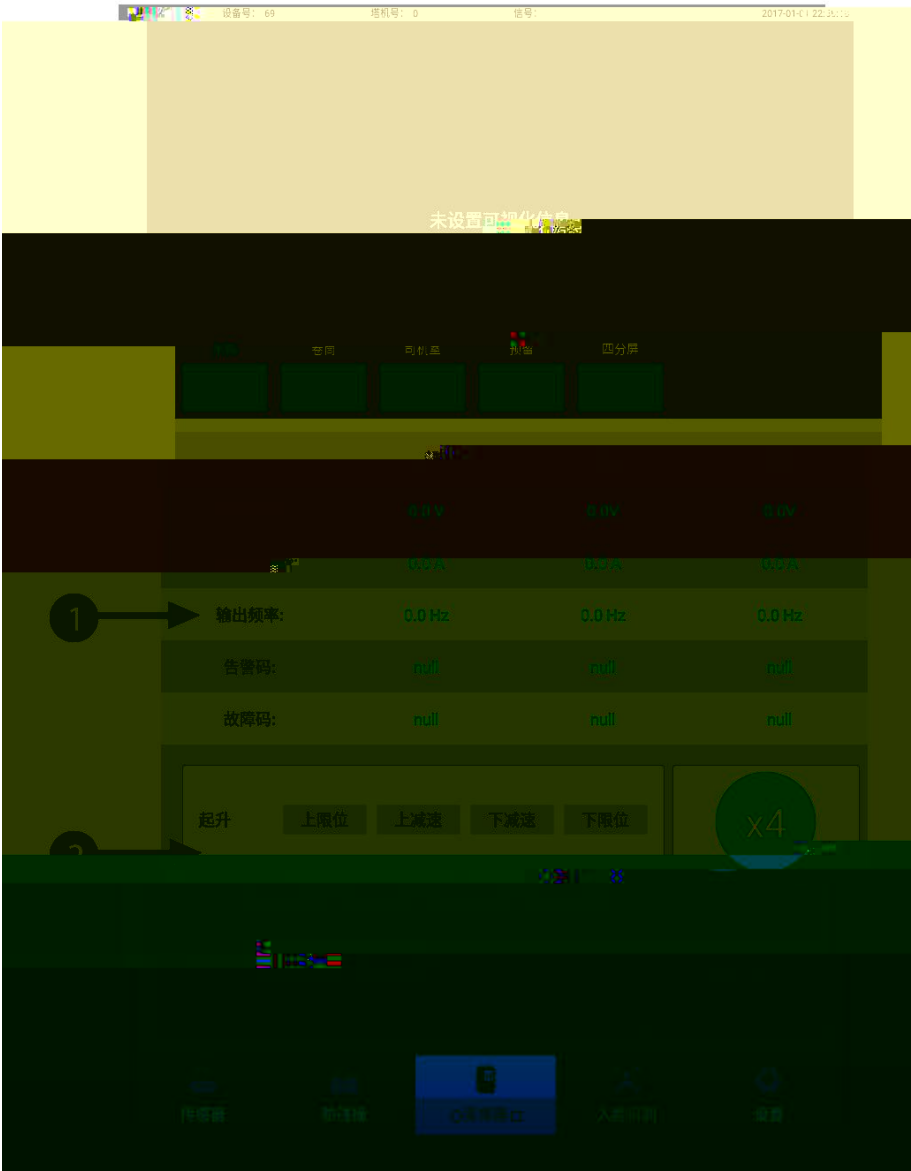
2.8



2.9



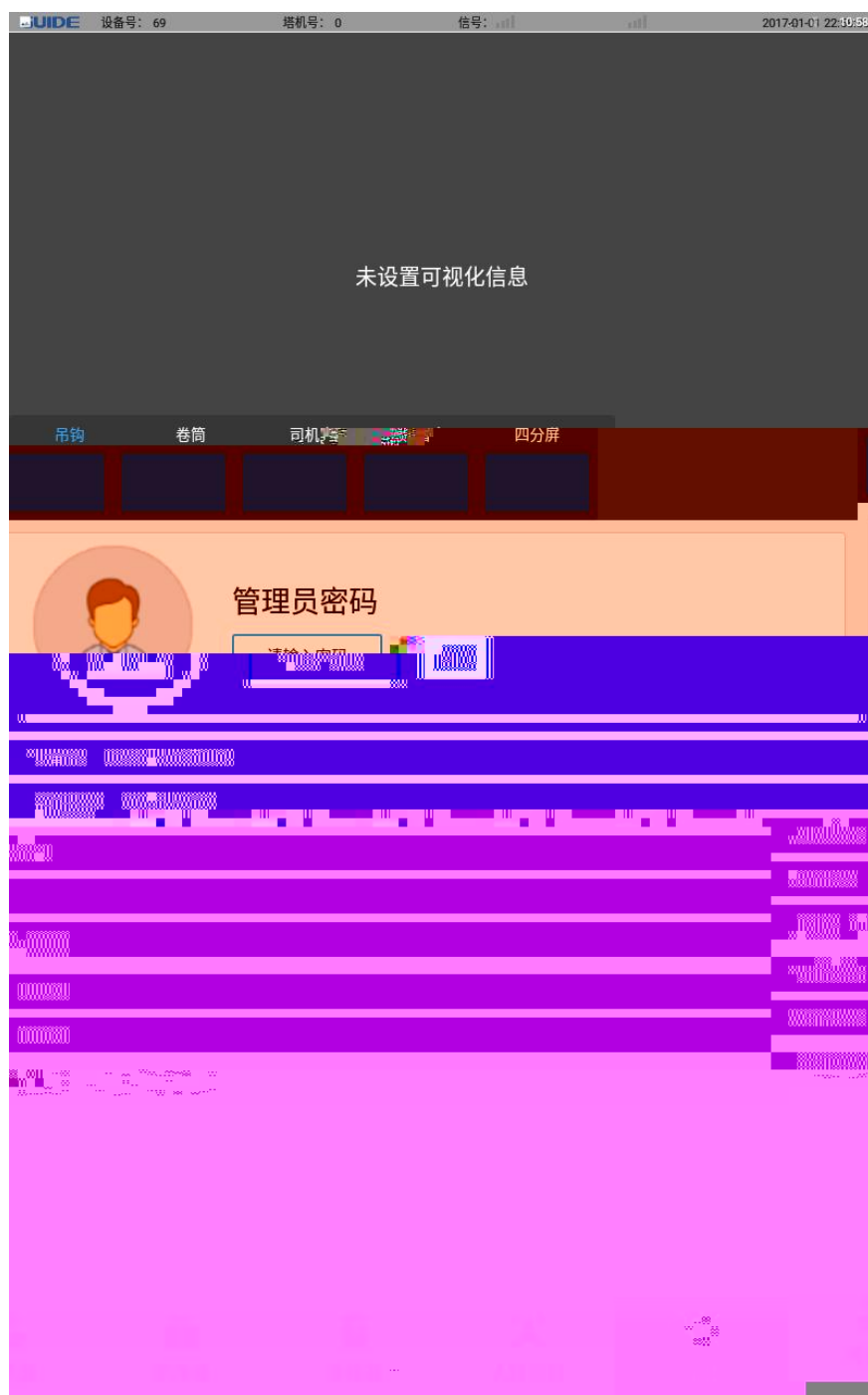
1.3



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2
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DI

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“ ”

3

3.1

设备号: 69 塔机号: 0 信号: 2017-01-01 22:59:35

<

设置

塔机基本信息

传感器标定

区域及防撞

其他



塔机类型: ●塔帽式 ●平头式 绳索倍率: ●2倍 ●4倍

GPS坐标X(经度)

13.4

备注: 小于六位数

GPS坐标Y(经度)

-32.14

备注: 小于六位数

塔身高度

70.00m

首节高度设置

10.00

m

增节高度设置

4.00

m

增节数量设置

15

节

塔帽高度设置

0.00

m备注: 起重臂下平面到塔尖距离

起重臂长度设置

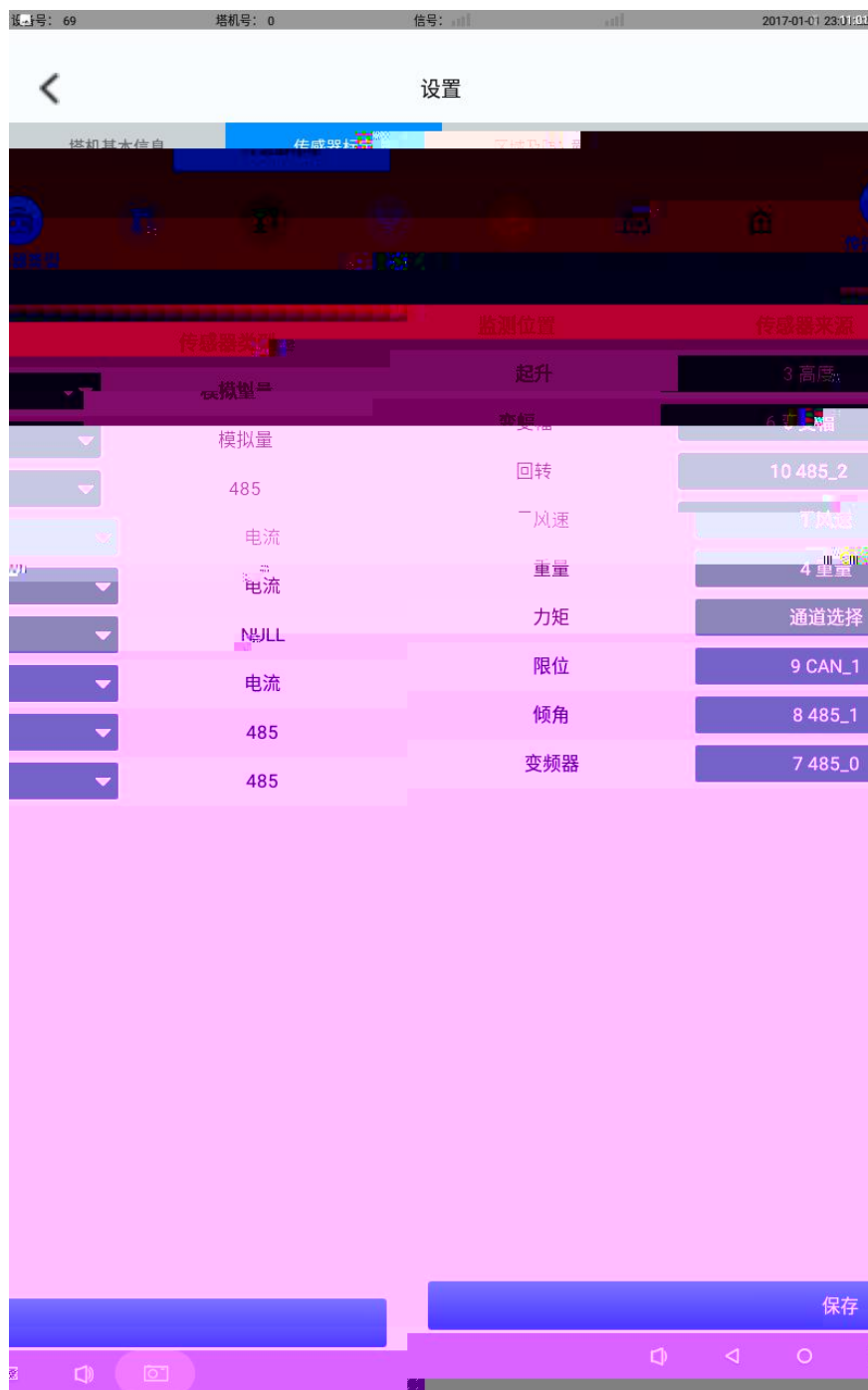
65.00

m

保存

“ ”

GPS



4.2



1

“ 1 ” “ 2 ” “ 3 ” “ 4 ” “ ”
” “

2 U

U “ calibrate_data ” Excel

U

” “

2

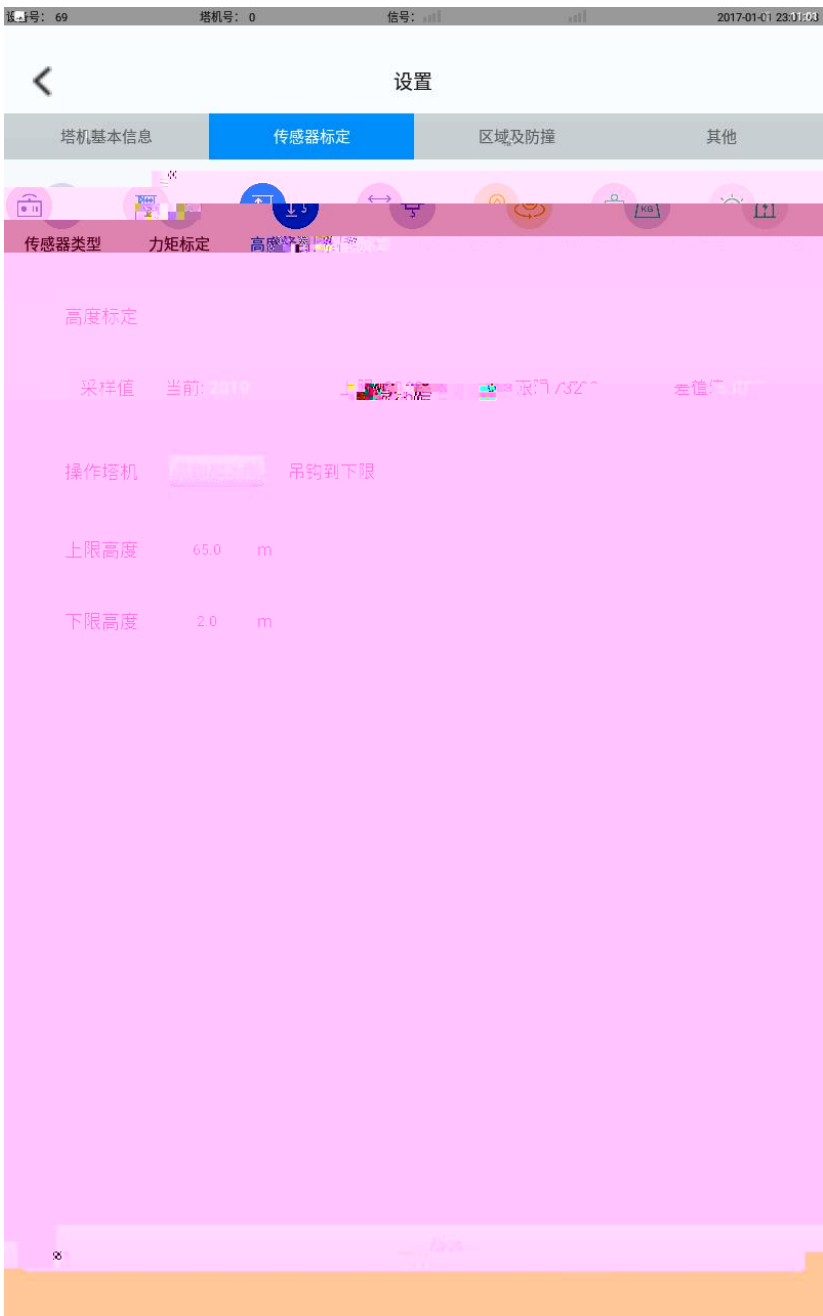


2

4

“ ”

4.3

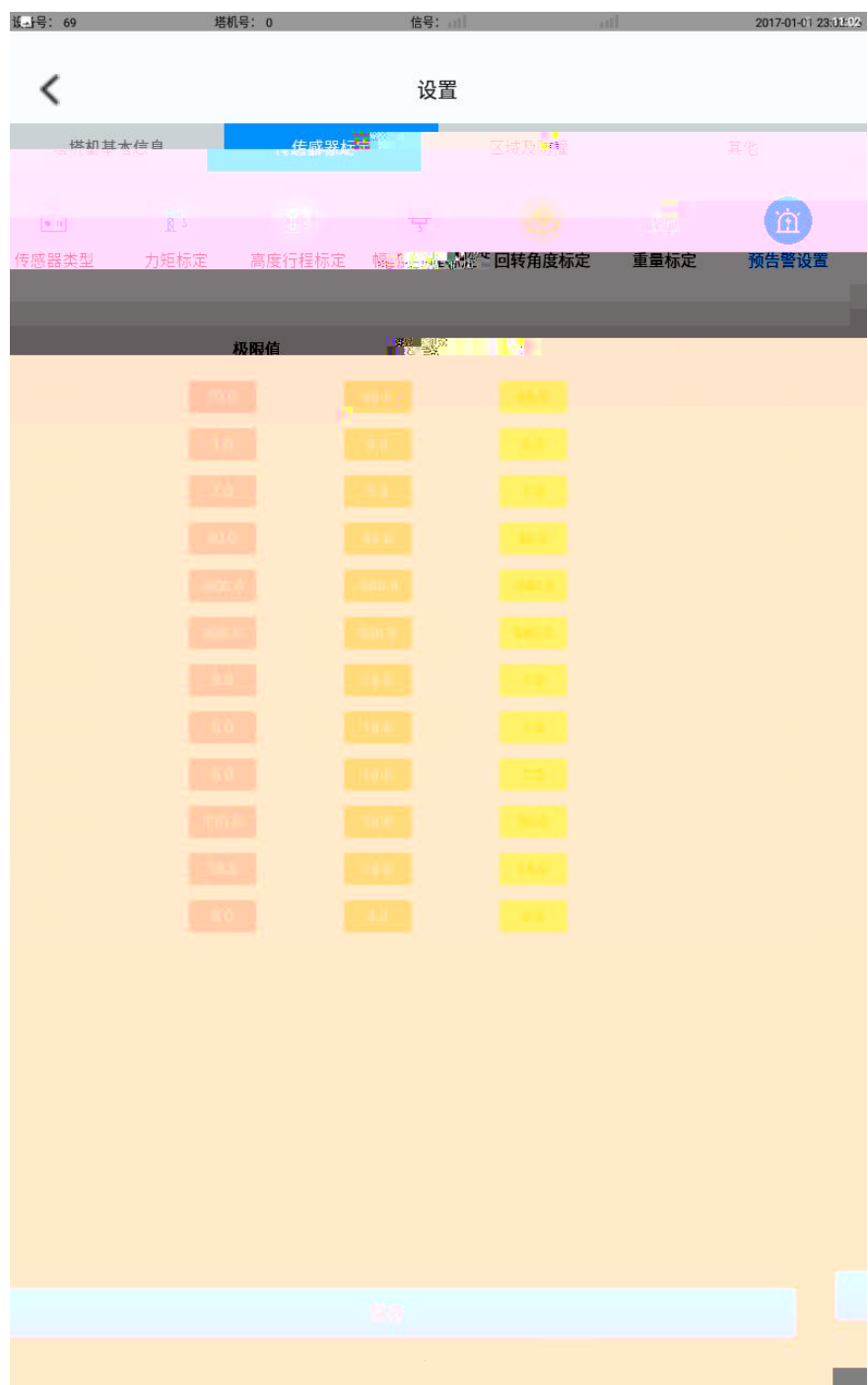


4.4





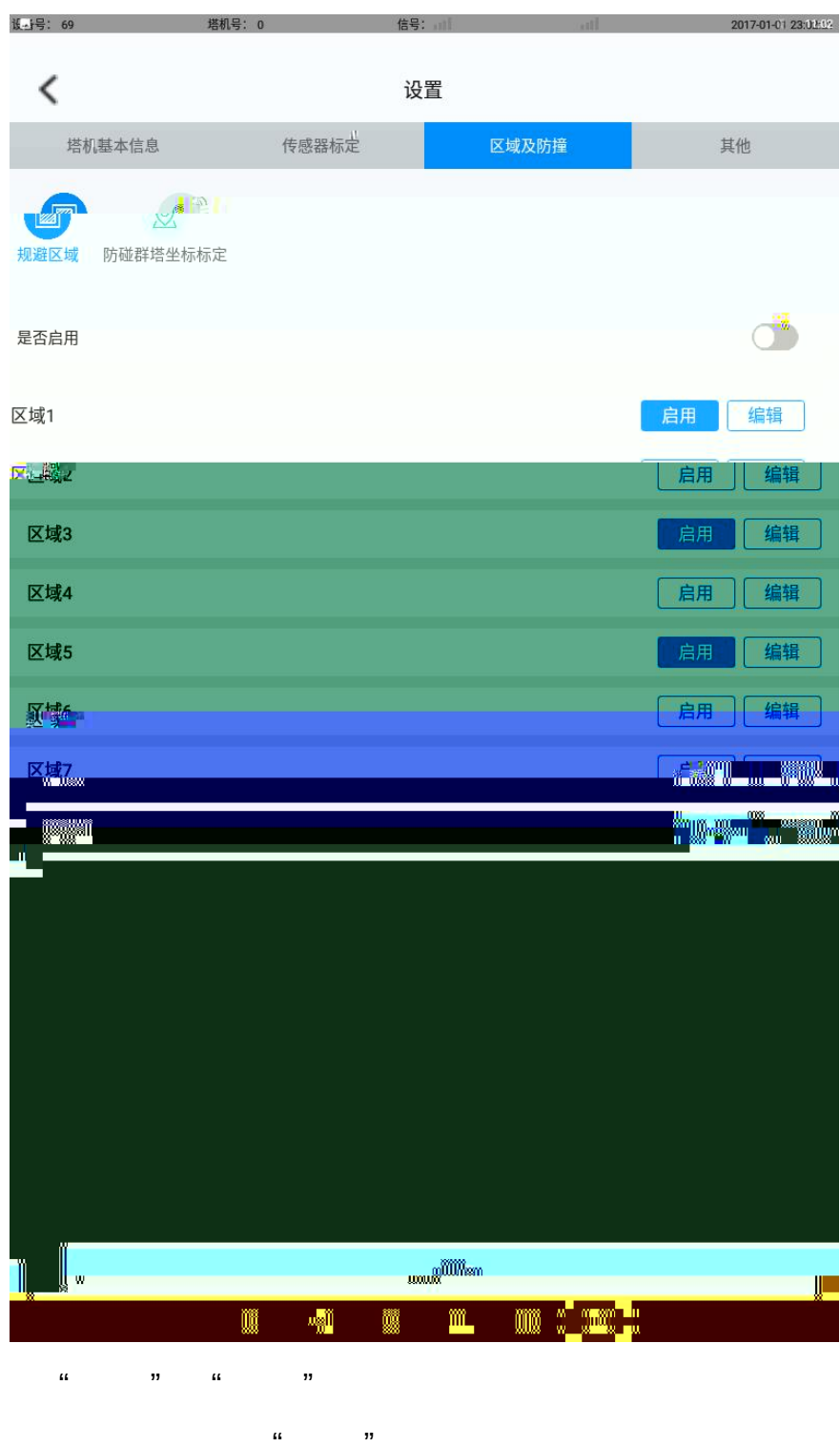
4.7



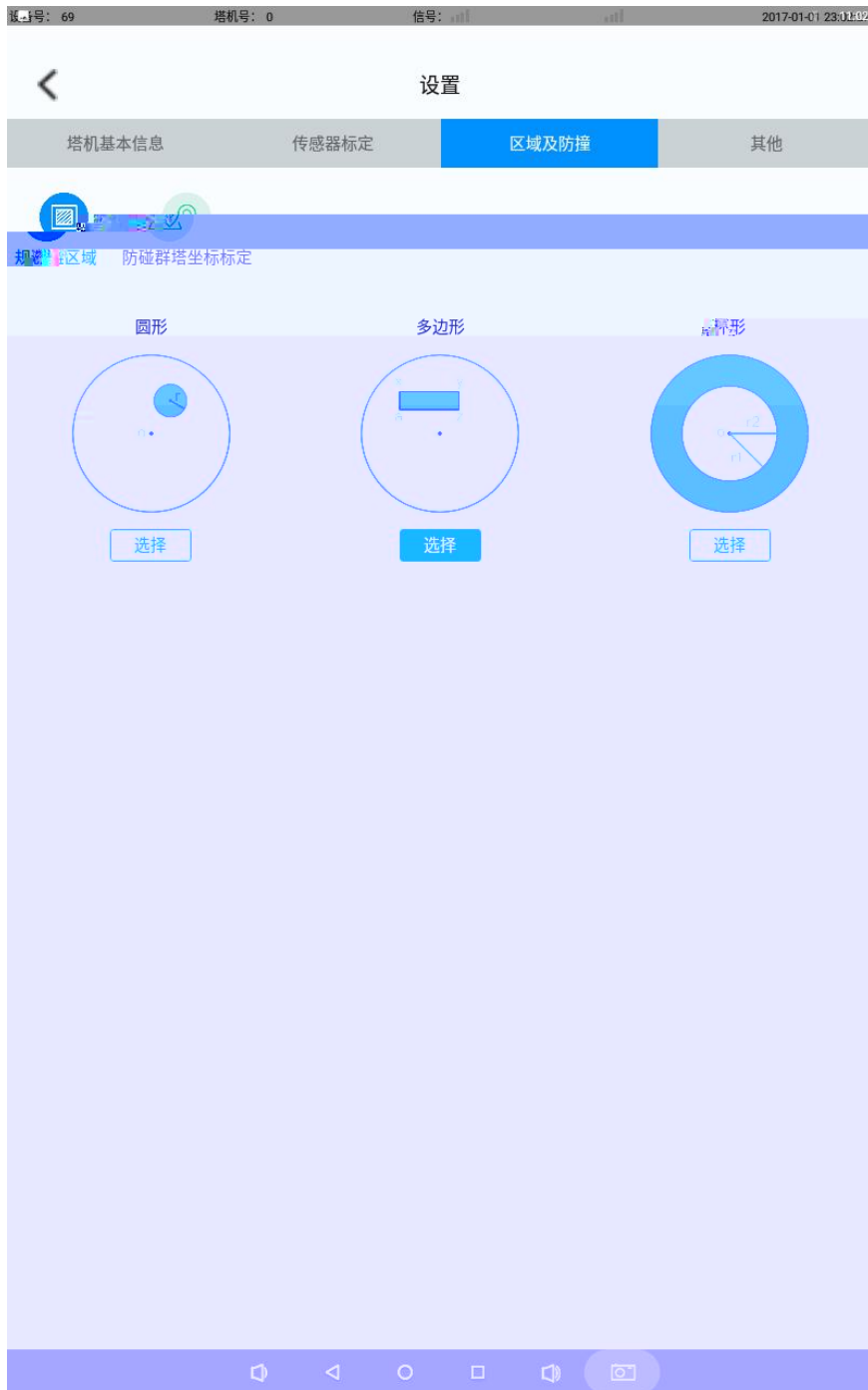
“ ”

5

5.1



8



站号: 69

塔机号: 0

信号:

2017-01-01 23:01:24

多边形

起升(m)

36.11

变幅(m)

23.01

回转(m)

-62.1

	X坐标	Y坐标	Z坐标	
点a	-0.33	-38.46	12.06	采集 清除
点b	28.29	-26.1	12.06	采集 清除
点c	14.18	19.09	37.0	采集 清除
点d	-31.16	10.13	12.06	采集 清除
点e	3.91	-23.92	20.77	采集 清除

允许驶入

是

否

吊钩允许驶入

是

否

保存

5

“ ”

“ ”



ID	1-16
RF	

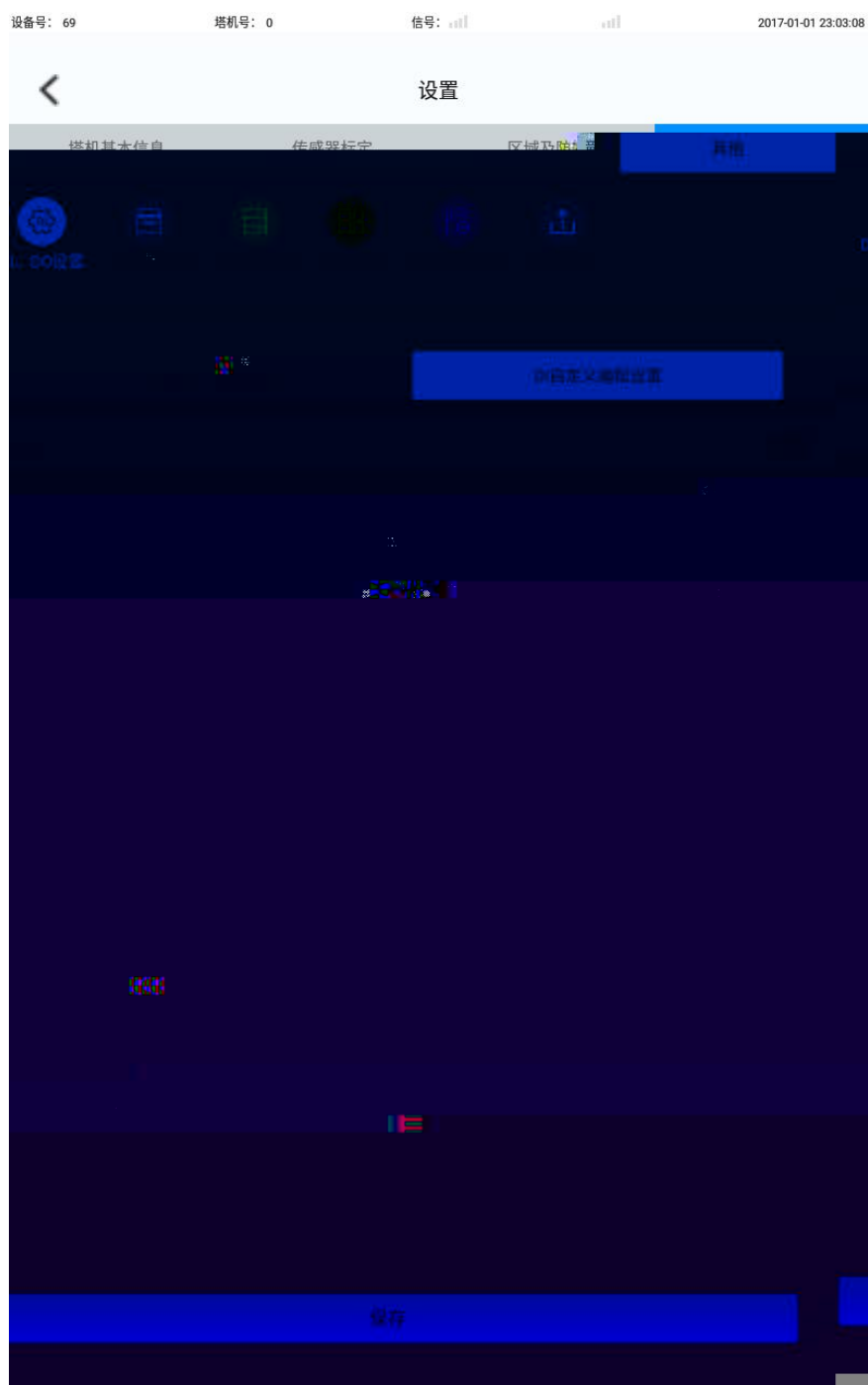
6.1 DI/DO

DI



DO

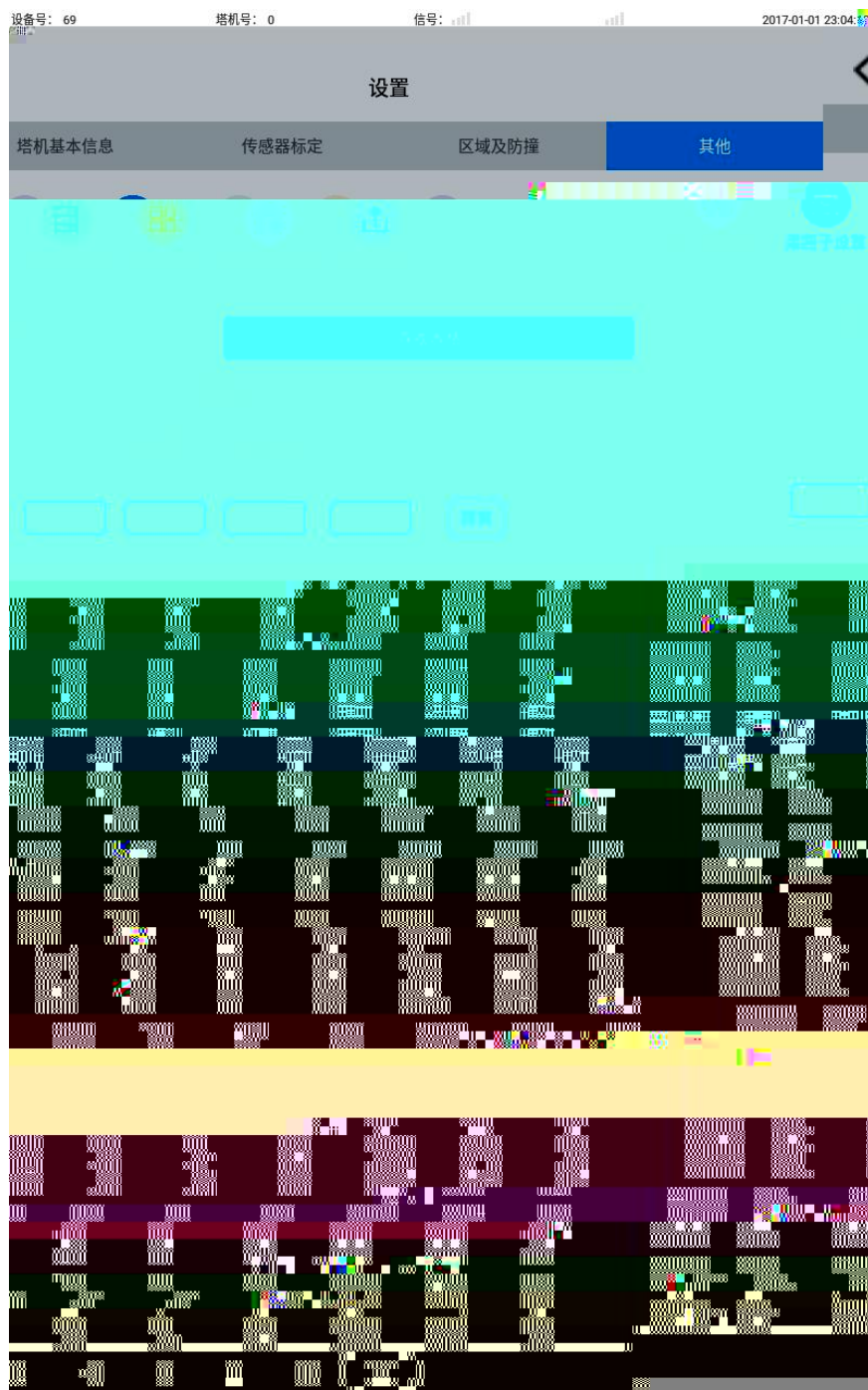
D0



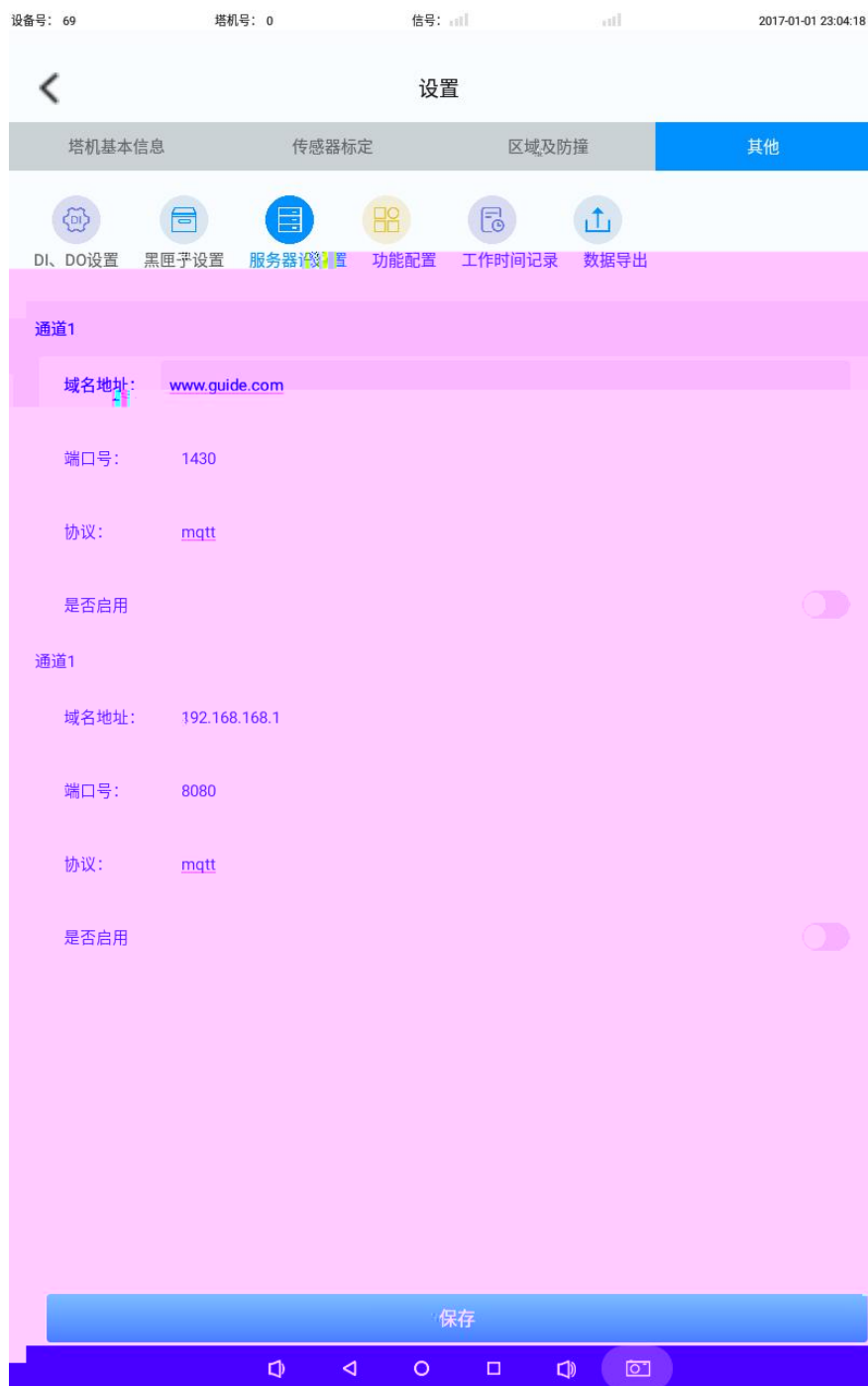
D1

6.2



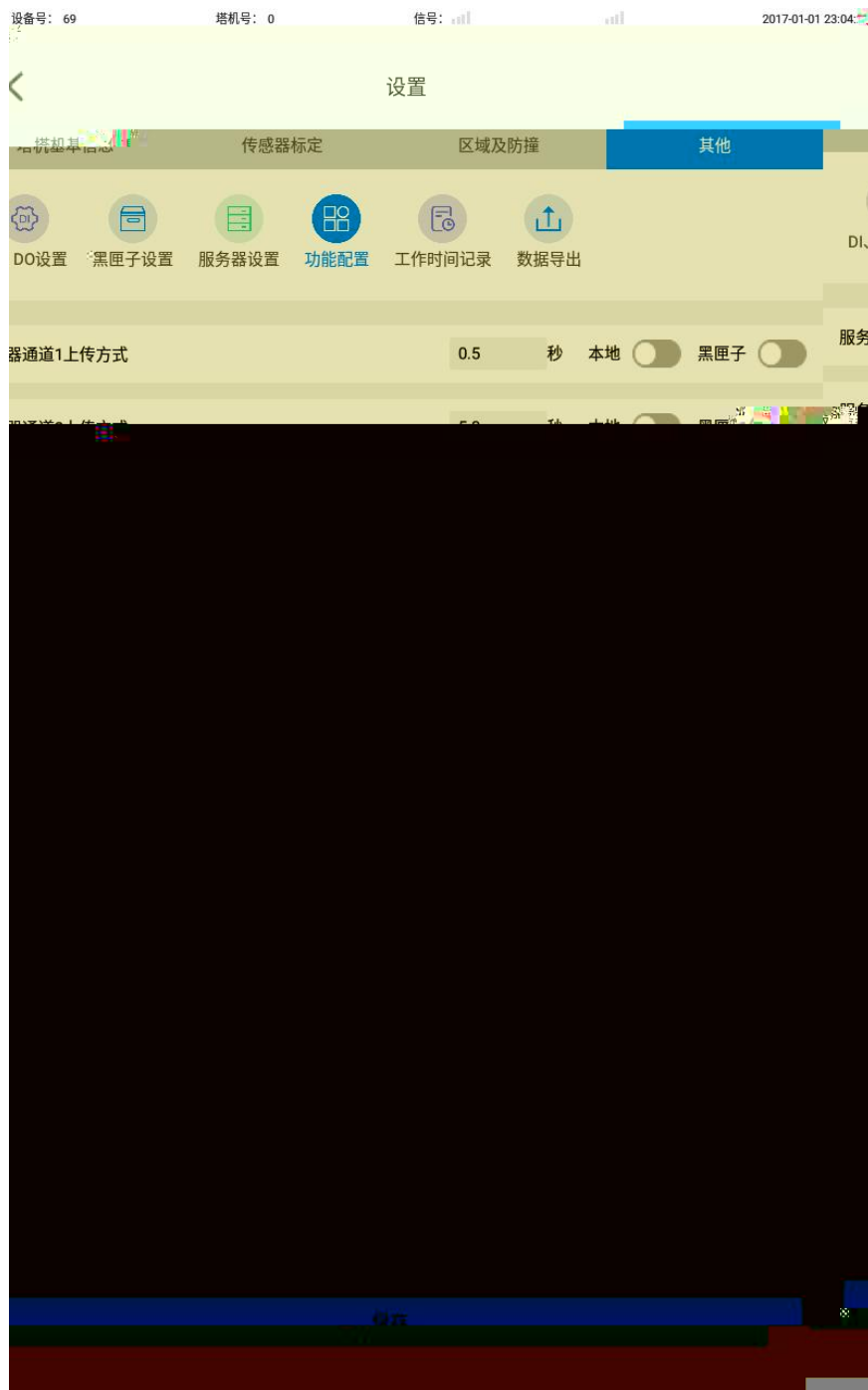


6.3

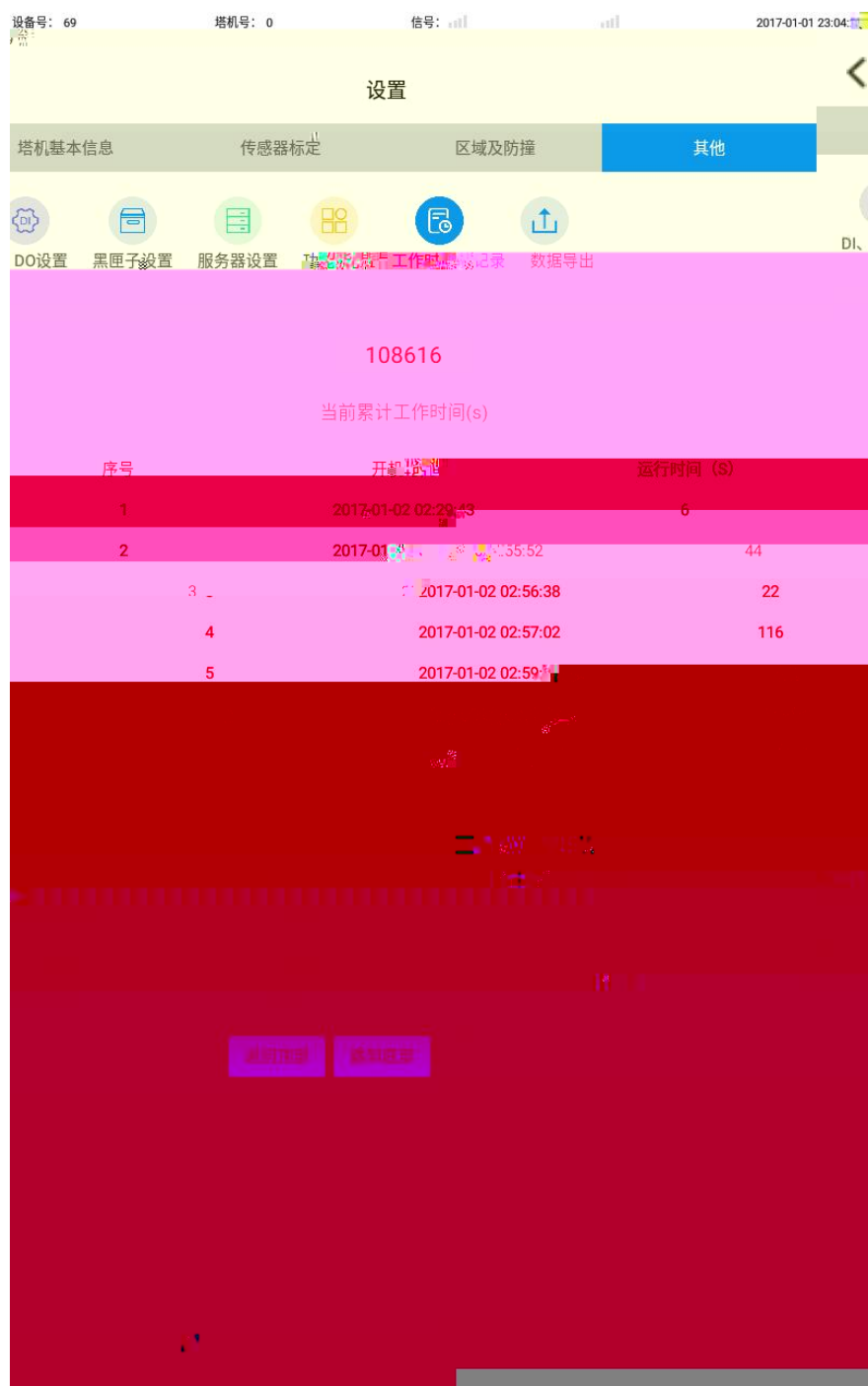


2

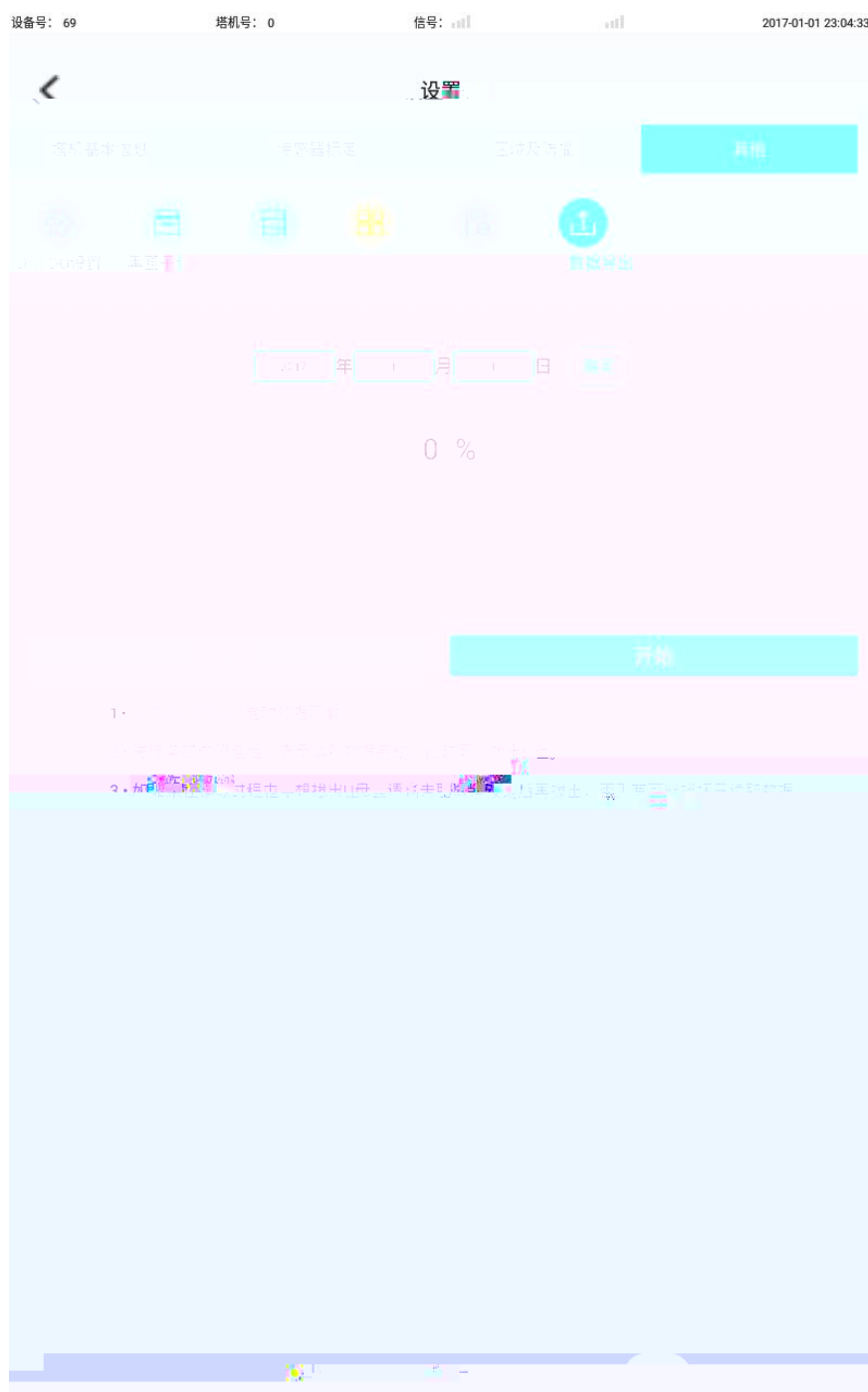
6.4



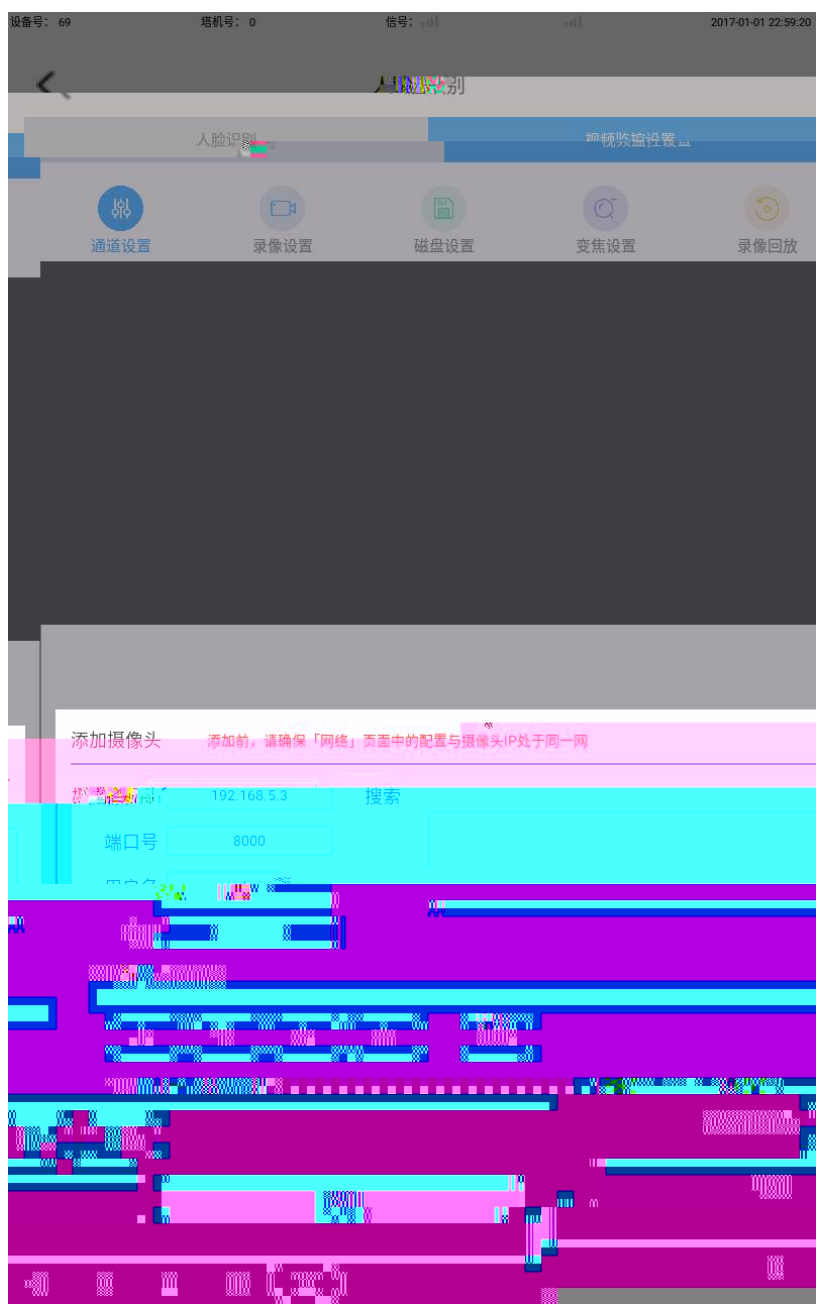
6.5



6.6



7.1



IP

1

IP

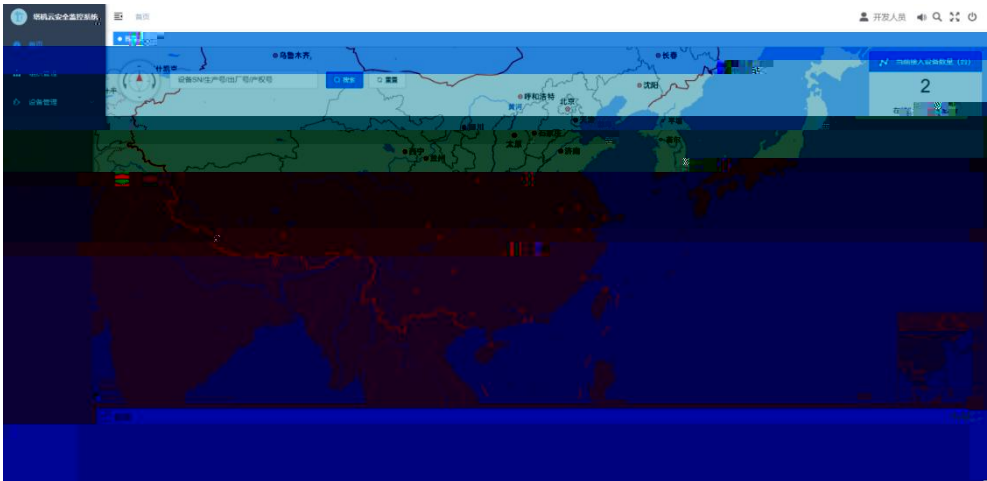
2

“ ”

IP

“ ”

“ ”



8.3

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- 1. ()
- 2. ()



2



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2



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8.4

